

2/16 FIG. 3 12 10 **ECU** 41 **MEMORY ANALOG INPUT** 42 **BUILT-IN SOFTWARE DIGITAL** INPUT 51 **ANALOG OUTPUT** \$ **·52** · **DATA DATA DIGITAL PROCESSOR** SENDING RECEIVING OUTPUT **EQUIPMENT EQUIPMENT** 15 13 14 20 ECU **DATA** DATA ANALOG SENDING RECEIVING **INPUT PROCESSOR** EQUIPMENT EQUIPMENT \$ **DIGITAL** INPUT **MEMORY ANALOG** OUTPUT **BUILT-IN SOFTWARE DIGITAL** OUTPUT

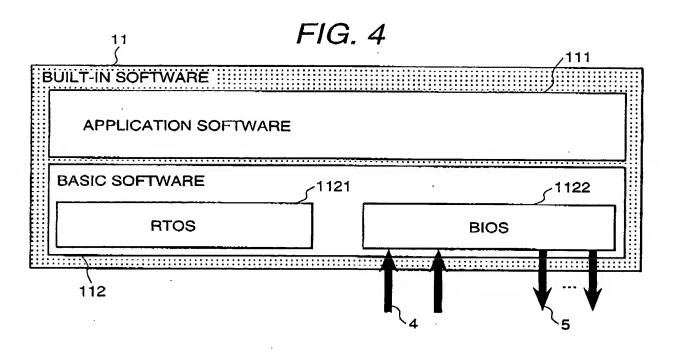
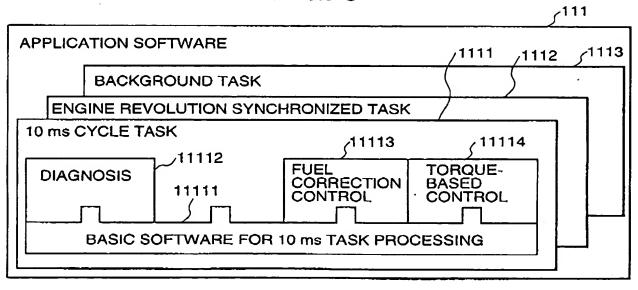
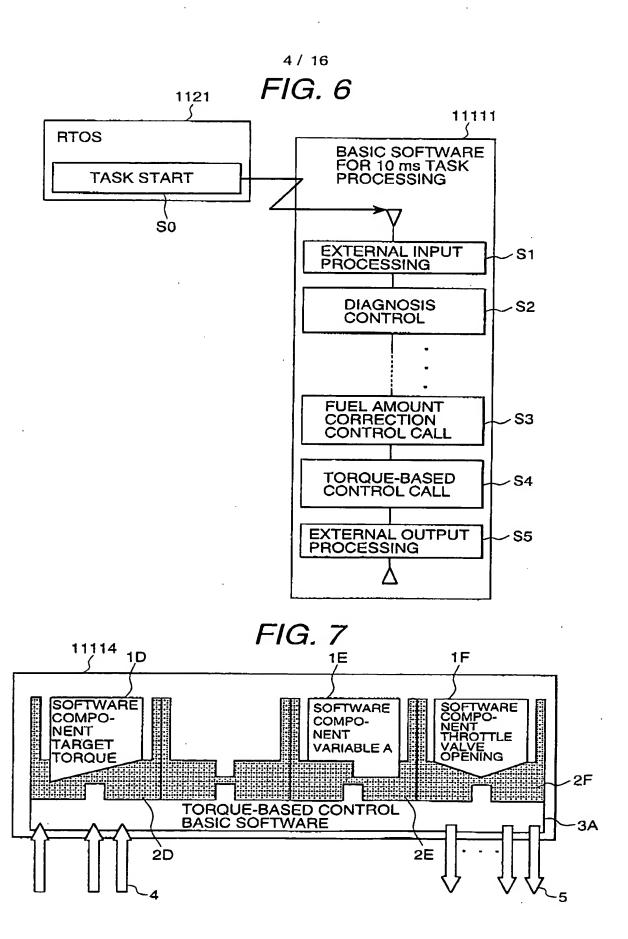


FIG. 5





```
extern void TVO_Calculate(unsigned short TargetTorque, ..., unsigend short Variable_A, unsigned short *TVO );

/* EOF */

void TVO_Calculate( unsigned short TargetTorque, ... C12

unsigend short Variable_A, unsigned short *TVO

unsigned short *TVO

*TVO=TargetTorque*Kt+Variable_A*Ka;

/* EOF */
```

```
unsigned short TVO;
                             C21
/* EOF*/
#define TVO_Get() TVO extern unsigned short TVO;
/* EOF*/
#include "TVO.h"
#include "TargetTorpue.h"
                                 -C23
#include "variableA.h"
#define TVO_Update() ¥
  TVO_Calculate(¥
   TargetTorque_Get(),¥
  varialbeA_Get(),¥
    &TVO¥
/*E0F*/
```

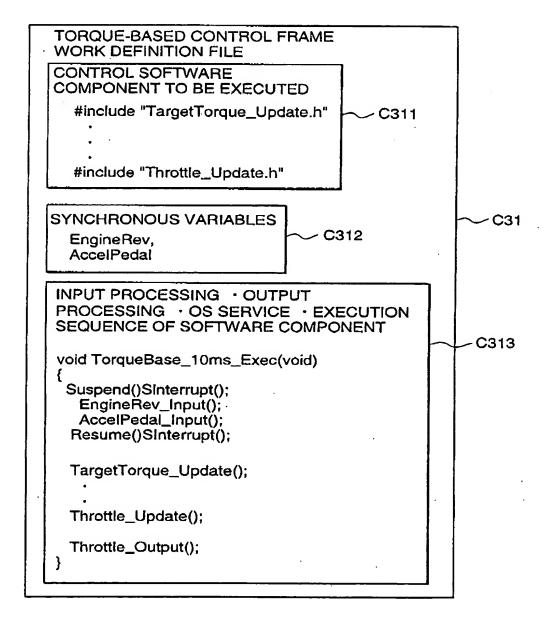


FIG. 11

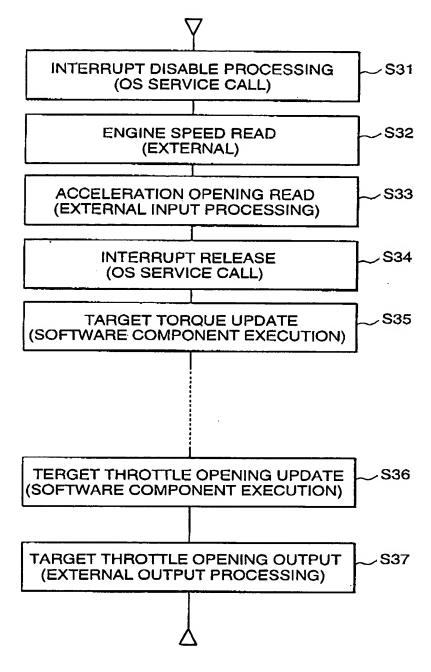


FIG. 12

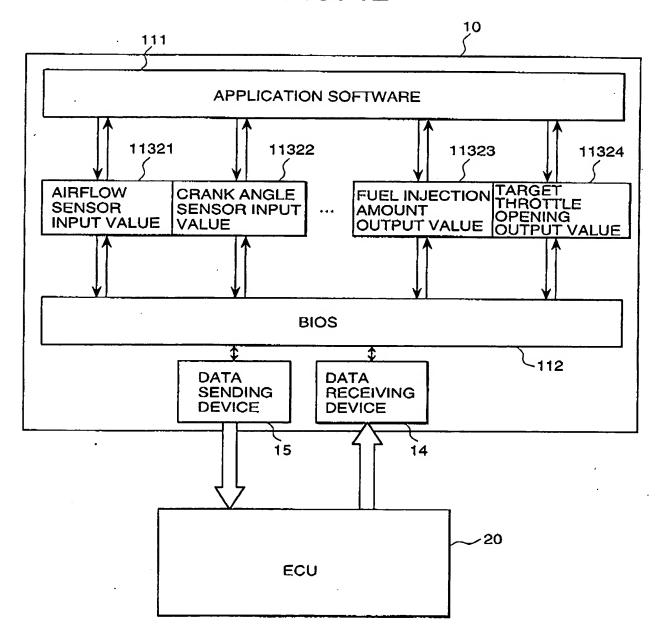


FIG. 13

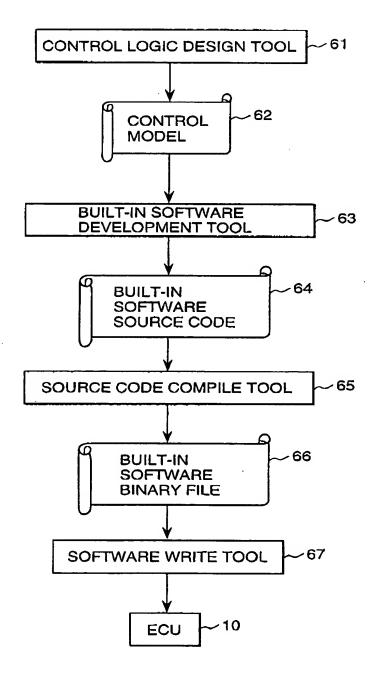


FIG. 14

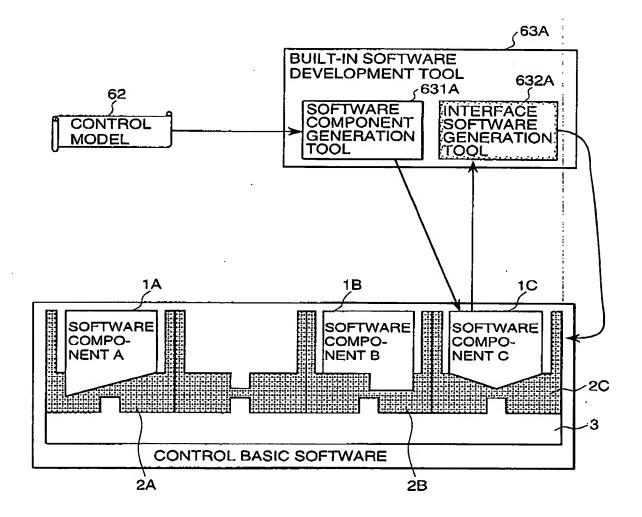


FIG. 15

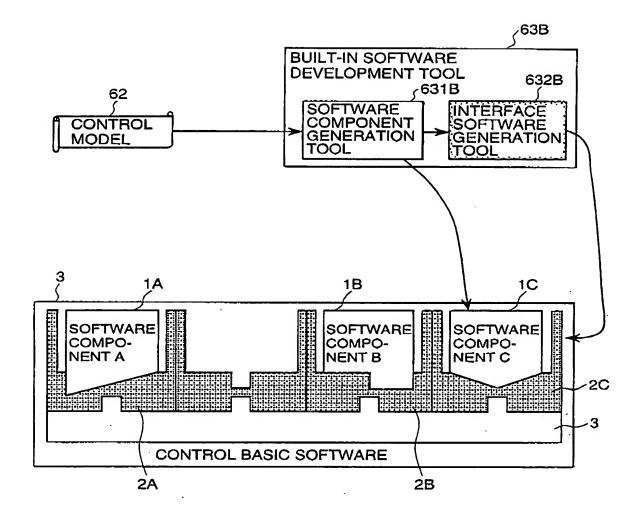
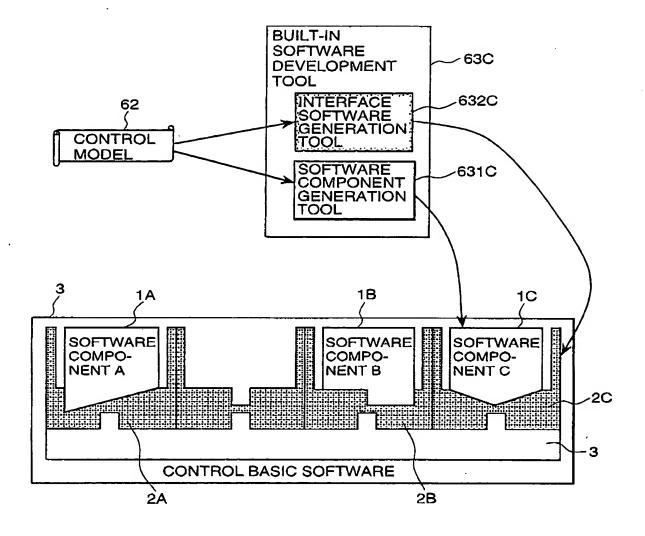
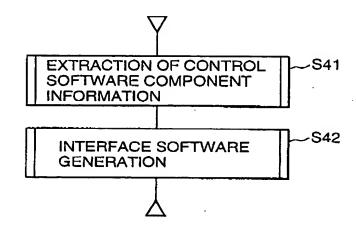


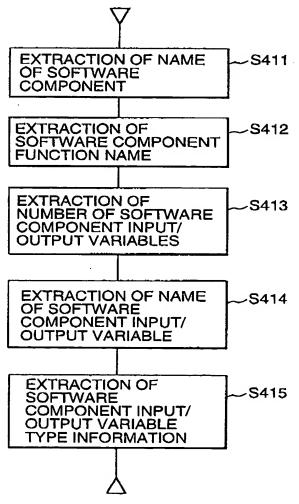
FIG. 16

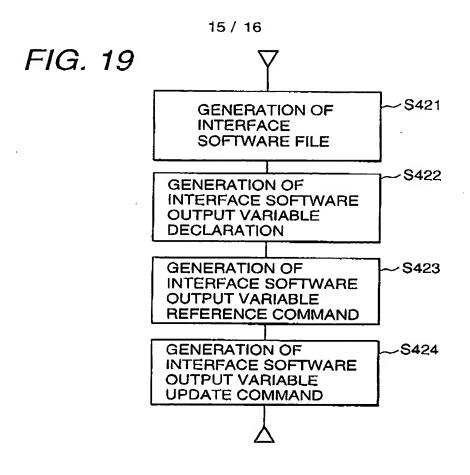


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FIG. 17







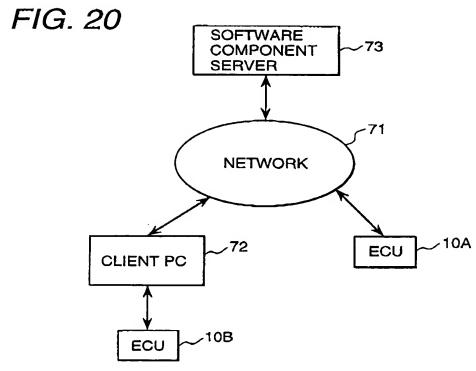


FIG. 21

